DEPRO eTorque Tool Class 7 DEP-DS-0568/01

Referenced standards: API 17H/17D, ISO 13628-8



Description:

Depro all electric Torque Tool (eTT) is designed to be operated by WROV. It has a standard interface (nose) according to API 17 H Short / API 17 D 1st Edition, ISO 13628-8.

eTT is powered from ROV and controlled topside via local webserver. This allows tool operation and data visualization in any web browser and ROV control system.

The smart system gives full control on torque, turns and speed. Allowing the operator to verify and document operational data.

Remote monitoring possibilities.

Torque tool is calibrated at delivery.

Features:

The Depro eTT benefits from many years of developing Torque Tools and is easaly integrated and operated through the customized HMI:

- Standard 115VAC ROV supply
- Integrated voltage monitoring/protection
- Web browser HMI, can be accessed via network
- Onboard server. Data logging. Generate report
- Absolute position, high resolution feedback
- Live torque feedback & monitoring
- High torque accuracy
- Integrated docking mode
- Target Torque, turn & speed
- Docking Mode/Nudge mode, Emergency stop
- Advanced brushless DC motor control



Depro AS is an expert in delivering tools and equipment for remote subsea operations. You can buy or rent standardized Depro products. You can also order bespoke designed products based on your drawings and IPs. We are an EPC partner. All services are available in-house!

eTorque Tool Class 7, DEP-DS-0568/01

Specification:

Torque range:	0 - 34 kNm
Calibrated range:	6,8 kNm - 34 kNm
Weight:	87 kg in air, 65 kg in water
Max water depth:	3000 m
Dimensions:	3D-model available on request
No Load Speed:	Up to 4,6 rpm
Direction of rotation:	Clockwise / Counter clockwise
Rotational indicator:	Yes (gear ratio 1:1)
Turn accuracy:	±0,75°
Torque accuracy:	±5% through the scale
Handle:	Adjustable Smarthandle (45° and 90°)
	(Fishtail available as addon)
Gear fluid:	Shell Omala HD 68 \ Tellus 32
Output interrface:	API 17H, API 17D and ISO 13628-8 : Class 7
Position:	Absolute
Position:	Resolver (on output shaft)
Temperature:	RTD Sensor
Torque:	Strain gauge
Power:	110-120VAC@ 2,3kW minimum
	110-120VAC@ 6,5kW maximum

Base Units:

- eTorque Tool Class 7

- eTorque Tool, Control canister

DEP-GA-0924 DEP-GA-1021

Adapters and addons:

A wide range of adaptes and addons are available for the electric driven Torque Tool (eTT). See specific datasheet: DEP-DS-PDS-00114

peration Setup						
tern Narroer 123456789 Operator Ola Nordmann Sutemit			Velocity [RPM]	Position [Turns]	Torque [Nm] 9800.4	
peration				RESET		
Docking Mode						
Direction CW v APPLY						Torque
Tun Lint		30,000				- Target Torque
0.000		25,000				
Target Torque (Nm) END 12000 C OPERATION	[um]	20,000				
0 - 34000 - Target Velocity (RPM)	Torque [Nm]	15,000				
2.1	70	10,000				
0.0 - 2.9		5,000				
peration Status		0				
Max Torque: 9810.6 [Nm]		28	B 302 305 308 312 3	5 318 32° 324 321 338 333 33	¹ 20 ⁸ 40 ² 40 ² 40 ⁹ 00 ⁶	
Max Velocity: 2.14 [RPM]				Time [s]		

Tools designed for submersion over long periods on request. Customized torque range on request.