## Electrical Motors, designed for subsea use.

## Description:

The electro motor is powered with $400 \mathrm{VAC}+10 \%$ and 3 phases 85 Hz . Equipped with encoder ( 2500 pulses / rotation) and temperature sensor (PT100). Standard IEC B5 mechanical interface. The enclosure is oil filled for connecting to external compensator. The design is made for subsea tooling. Equipment for submersion over long periods on request.


## Specification:

| Depro Drawing: | DEP-A-0966 | DEP-A-1419 | Dep-A-1420 |
| :--- | :--- | :--- | :--- |
| Energy Consumptions: | 1 kW | 4 kW | 9 kW |
| Power factor $\cos -\varphi: \square$ | 0,66 | 0,65 | 0,72 |
| Rotations RPM: | 2914 | 2445 | 2586 |
| Max Torque: | 6 nM | 32 nM | 64 nM |
| Weight in air: | 15 kg | 27 kg | 39 kg |
| Dimensions LxØ: | $320 \mathrm{x} \varnothing 160 \mathrm{~mm}$ | $390 \mathrm{x} \varnothing 200 \mathrm{~mm}$ | $445 \mathrm{x} \varnothing 250 \mathrm{~mm}$ |
| Dimensions Rotor Axle: | $\varnothing 14 \mathrm{~mm}$ | $\varnothing 24 \mathrm{~mm}$ | $\varnothing 28 \mathrm{~mm}$ |
| Material House: | AL 6082 T 6 | AL 6082 T 6 | AL 6082 T 6 |
| Material Axle: | $1.4418(\mathrm{~S} 165 \mathrm{M})$ | $1.4418(\mathrm{~S} 165 \mathrm{M})$ | $1.4418(\mathrm{~S} 165 \mathrm{M})$ |
| IEC Interface: | $571-\mathrm{B5}$ | $590-\mathrm{B5}$ | $5100-\mathrm{B5}$ |
| Max Water Depth: | 4000 m | 4000 m | 4000 m |

